

# Introduction to Programming (in C++)

## *Numerical algorithms*

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# Product of polynomials

- Given two polynomials on one variable and real coefficients, compute their product

(we will decide later how we represent polynomials)

- Example: given  $x^2 + 3x - 1$  and  $2x - 5$ , obtain

$$2x^3 - 5x^2 + 6x^2 - 15x - 2x + 5 = 2x^3 + x^2 - 17x + 5$$

# Product of polynomials

- Key point:

$$\text{Given } p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

$$\text{and } q(x) = b_m x^m + b_{m-1} x^{m-1} + \dots + b_1 x + b_0,$$

what is the coefficient  $c_i$  of  $x^i$  in  $(p * q)(x)$  ?

- We obtain  $x^{i+j}$  whenever we multiply  $a_i x^i \cdot b_j x^j$
- Idea: for every  $i$  and  $j$ , add  $a_i \cdot b_j$  to the  $(i+j)$ -th coefficient of the product polynomial.

# Product of polynomials

- Suppose we represent a polynomial of degree  $n$  by a vector of size  $n+1$ .

That is,  $v[0..n]$  represents the polynomial

$$v[n] x^n + v[n-1] x^{n-1} + \dots + v[1] x + v[0]$$

- We want to make sure that  $v[v.size() - 1] \neq 0$  so that  $\text{degree}(v) = v.size() - 1$
- The only exception is the constant-0 polynomial. We'll represent it by a vector of size 0.

# Product of polynomials

---

```
typedef vector<double> Polynomial;  
  
// Pre: --  
// Returns p*q  
Polynomial product(const Polynomial& p,  
                   const Polynomial& q);
```

# Product of polynomials

```
Polynomial product(const Polynomial& p, const Polynomial& q) {  
  
    // Special case for a polynomial of size 0  
    if (p.size() == 0 or q.size() == 0) return Polynomial(0);  
    else {  
        int deg = p.size() - 1 + q.size() - 1; // degree of p*q  
        Polynomial r(deg + 1, 0);  
        for (int i = 0; i < p.size(); ++i) {  
            for (int j = 0; j < q.size(); ++j) {  
                r[i + j] = r[i + j] + p[i]*q[j];  
            }  
        }  
        return r;  
    }  
}
```

```
// Invariant (of the outer loop): r = product p[0..i-1]*q  
// (we have used the coefficients p[0] ... p[i-1])
```

# Sum of polynomials

- Note that over the real numbers,  
 $\text{degree}(p*q) = \text{degree}(p) + \text{degree}(q)$   
(except if  $p = 0$  or  $q = 0$ ).

So we know the size of the result vector from the start.

- This is not true for the polynomial sum, e.g.

$$\text{degree}((x + 5) + (-x - 1)) = 0$$

# Sum of polynomials

```
// Pre: --
// Returns p+q
Polynomial sum(const Polynomial& p, const Polynomial& q);
    int maxdeg = max(p.size(), q.size()) - 1;
    int deg = -1;
    Polynomial r(maxdeg + 1, 0);

    // Inv r[0..i-1] = (p+q)[0..i-1] and
    // deg = largest j s.t. r[j] != 0 (or -1 if none exists)
    for (int i = 0; i <= maxdeg; ++i) {
        if (i >= p.size()) r[i] = q[i];
        else if (i >= q.size()) r[i] = p[i];
        else r[i] = p[i] + q[i];
        if (r[i] != 0) deg = i;
    }

    Polynomial rr(deg + 1);
    for (int i = 0; i <= deg; ++i) rr[i] = r[i];
    return rr;
}
```

# Sum of sparse vectors

- In some cases, problems must deal with sparse vectors or matrices (most of the elements are zero).
- Sparse vectors and matrices can be represented more efficiently by only storing the non-zero elements. For example, a vector can be represented as a vector of pairs (index, value), sorted in ascending order of the indices.
- Example:

$[0, 0, 1, 0, -3, 0, 0, 0, 2, 0, 0, 4, 0, 0, 0]$

can be represented as

$[(2, 1), (4, -3), (8, 2), (11, 4)]$

# Sum of sparse vectors

- Design a function that calculates the sum of two sparse vectors, where each non-zero value is represented by a pair (index, value):

```
struct Pair {  
    int index;  
    int value;  
}
```

```
typedef vector<Pair> SparseVector;
```

# Sum of sparse vectors

```
// Pre: --  
// Returns v1+v2
```

```
SparseVector sparse_sum(const SparseVector& v1,  
                        const SparseVector& v2);
```

```
// Inv: p1 and p2 will point to the first  
//      non-treated elements of v1 and v2.  
//      vsum contains the elements of v1+v2 treated so far.  
//      psum points to the first free location in vsum.
```

- Strategy:
  - Calculate the sum on a sufficiently large vector.
  - Copy the result on another vector of appropriate size.

# Sum of sparse vectors

```
SparseVector sparse_sum(const SparseVector& v1, const SparseVector& v2) {
    SparseVector vsum;
    int p1 = 0, p2 = 0;

    while (p1 < v1.size() and p2 < v2.size()) {
        if (v1[p1].index < v2[p2].index) { // Element only in v1
            vsum.push_back(v1[p1]);
            ++p1;
        }
        else if (v1[p1].index > v2[p2].index) { // Element only in v2
            vsum.push_back(v2[p2]);
            ++p2;
        }
        else { // Element in both
            Pair p;
            p.index = v1[p1].index;
            p.value = v1[p1].value + v2[p2].value;
            if (p.value != 0) vsum.push_back(p);
            ++p1; ++p2;
        }
    }
}
```

# Sum of sparse vectors

```
// Copy the remaining elements of v1
while (p1 < v1.size()) {
    vsum.push_back(v1[p1]);
    ++p1;
}

// Copy the remaining elements of v2
while (p2 < v2.size()) {
    vsum.push_back(v2[p2]);
    ++p2;
}

return vsum;
}
```

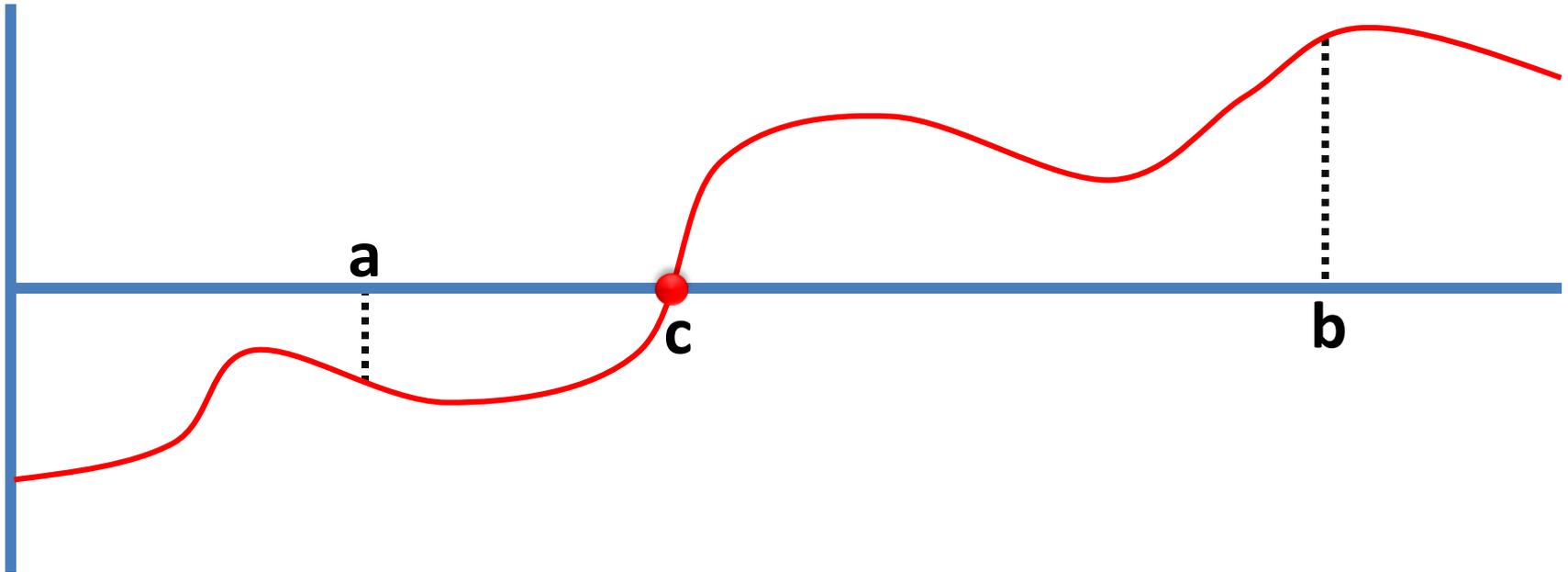
# Root of a continuous function

## Bolzano's theorem:

Let  $f$  be a real-valued continuous function.

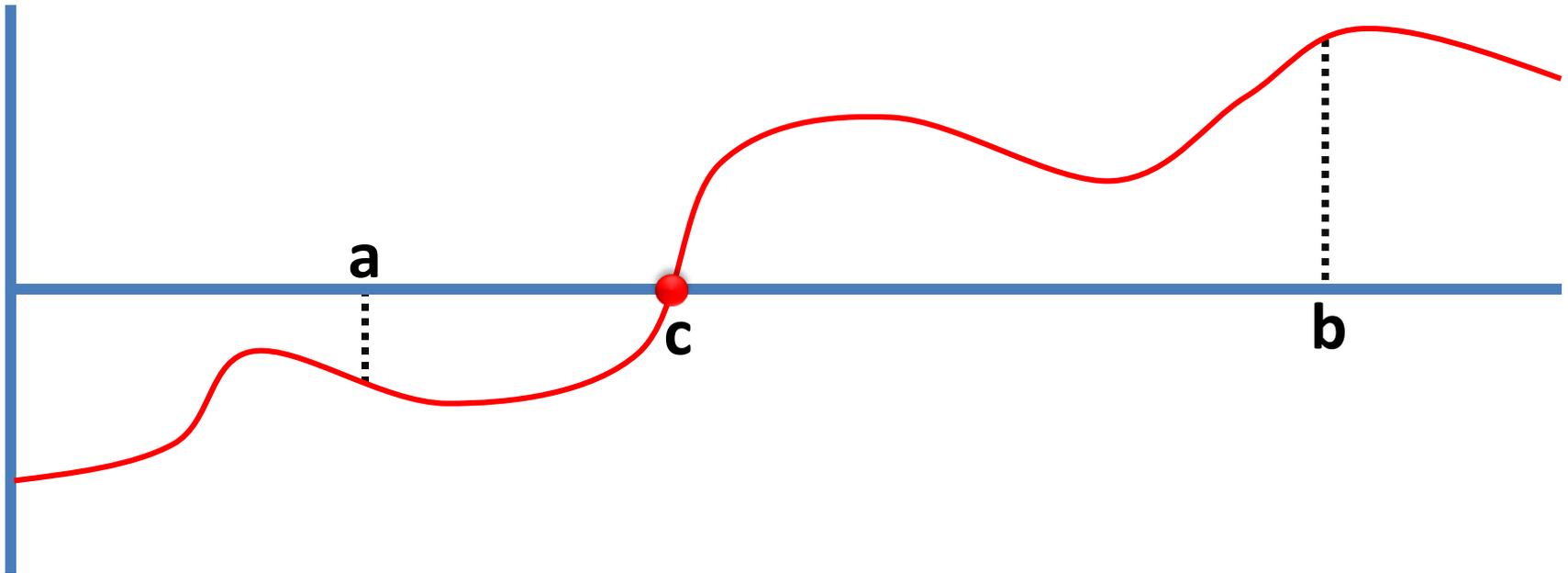
Let  $a$  and  $b$  be two values such that  $a < b$  and  $f(a) \cdot f(b) < 0$ .

Then, there is a value  $c \in [a, b]$  such that  $f(c) = 0$ .



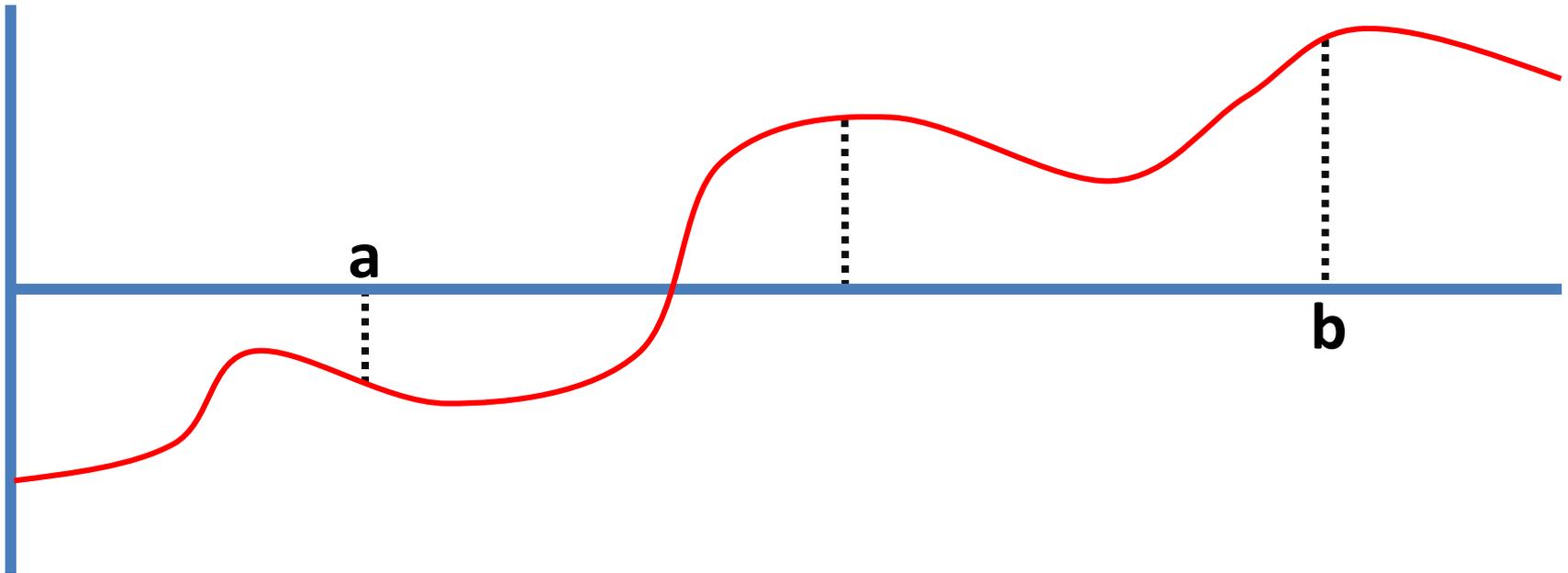
# Root of a continuous function

Design a function that finds a root of a continuous function  $f$  in the interval  $[a, b]$  assuming the conditions of Bolzano's theorem are fulfilled. Given a precision ( $\varepsilon$ ), the function must return a value  $c$  such that the root of  $f$  is in the interval  $[c, c+\varepsilon]$ .



# Root of a continuous function

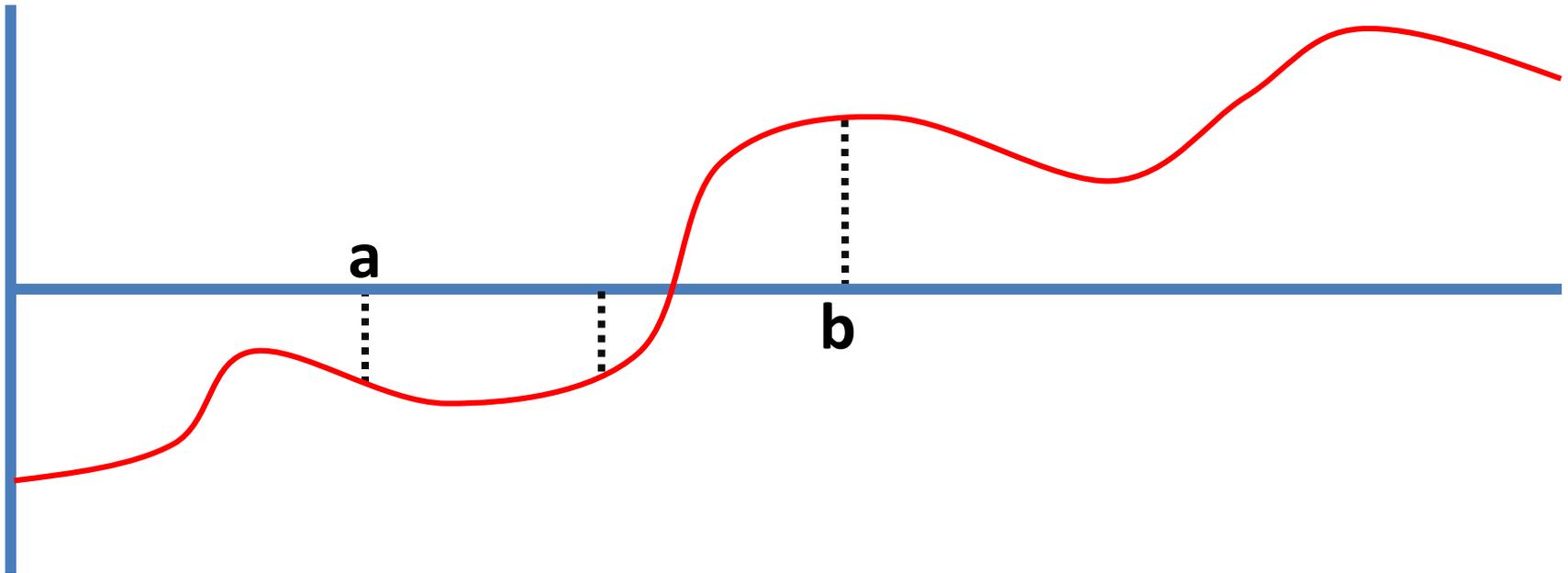
**Strategy:** narrow the interval  $[a, b]$  by half, checking whether the value of  $f$  in the middle of the interval is positive or negative. Iterate until the width of the interval is smaller  $\varepsilon$ .



# Root of a continuous function

```
// Pre:  $f$  is continuous,  $a < b$  and  $f(a)*f(b) < 0$ .  
// Returns  $c \in [a, b]$  such that a root exists in the  
// interval  $[c, c + \epsilon]$ .
```

```
// Inv: a root of  $f$  exists in the interval  $[a, b]$ 
```



# Root of a continuous function

```
double root(double a, double b, double epsilon) {
    while (b - a > epsilon) {
        double c = (a + b)/2;
        if (f(a)*f(c) <= 0) b = c;
        else a = c;
    }
    return a;
}
```

# Root of a continuous function

**// A recursive version**

```
double root(double a, double b, double epsilon) {  
    if (b - a <= epsilon) return a;  
    double c = (a + b)/2;  
    if (f(a)*f(c) <= 0) return root(a,c,epsilon);  
    else return root(c,b,epsilon);  
}
```

# Barcode

- A barcode is an optical machine-readable representation of data. One of the most popular encoding systems is the UPC (Universal Product Code).
- A UPC code has 12 digits. Optionally, a check digit can be added.



# Barcode

- The check digit is calculated as follows:
  1. Add the digits in odd-numbered positions (first, third, fifth, etc.) and multiply by 3.
  2. Add the digits in the even-numbered positions (second, fourth, sixth, etc.) to the result.
  3. Calculate the result modulo 10.
  4. If the result is not zero, subtract the result from 10.
- Example: 380006571113
  - $(3+0+0+5+1+1)*3 = 30$
  - $8+0+6+7+1+3 = 25$
  - $(30+25) \bmod 10 = 5$
  - $10 - 5 = 5$

# Barcode

---

- Design a program that reads a sequence of 12-digit numbers that represent UPCs without check digits and writes the same UPCs with the check digit.
- Question: do we need a data structure to store the UPCs?
- Answer: no, we only need a few auxiliary variables.

# Barcode

- The program might have a loop treating a UPC at each iteration. The invariant could be as follows:

```
// Inv: all the UPCs of the treated codes  
//       have been written.
```

- At each iteration, the program could read the UPC digits and, at the same time, write the UPC and calculate the check digit. The invariant could be:

```
// Inv: all the treated digits have been  
//       written. The partial calculation of  
//       the check digit has been performed  
//       based on the treated digits.
```

# Barcode

// Pre: the input contains a sequence of UPCs without check digits.  
// Post: the UPCs at the input have been written with their check digits.

```
int main() {
    char c;
    while (cin >> c) {
        cout << c;
        int d = 3*(int(c) - int('0')); // first digit in an odd location
        for (int i = 2; i <= 12; ++i) {
            cin >> c;
            cout << c;
            if (i%2 == 0) d = d + int(c) - int('0');
            else d = d + 3*(int(c) - int('0'));
        }
        d = d%10;
        if (d > 0) d = 10 - d;
        cout << d << endl;
    }
}
```